


Automated Performance Prediction for Model-Driven Engineering of Real-Time Embedded Systems

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Overview



- ❖ Embedded Systems Modeling
- ❖ Software Performance Engineering (SPE) Overview
- ❖ Automating the Model-Driven Analysis
- ❖ Proof of Concept: Component-based RTES

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Embedded Systems Performance



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ES Software Industry Challenges

- ❖ ES revolution started in industry rather than universities
 - ♦ Common systems engineering problems haven't been scientifically addressed
- ❖ Shift from Hardware to Software ("softwareization")
- ❖ Dramatic increase in the complexity of functionality
 - ♦ Number of lines of code per function in aircraft systems was 10 in 1970, now 1,000,000
 - ♦ Increase in observable, controllable parameters
 - ♦ Trend to interoperability of ES in networks
- ❖ Growing gap between software size and developers' productivity

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Why Worry About Performance?

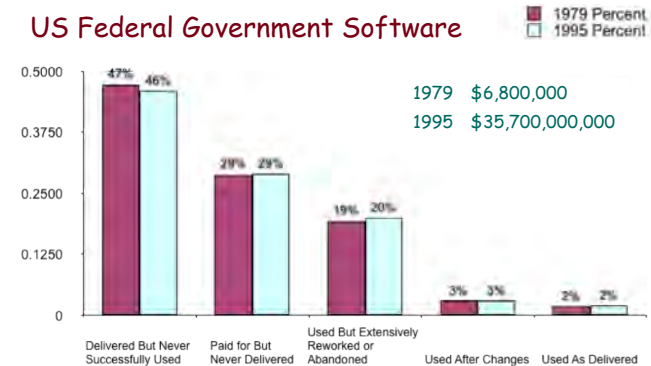
- ❖ Many systems experience performance problems on initial release
 - ◆ Introduced early in development
 - ◆ Not discovered until late
- ❖ Problems are often due to fundamental architecture or design rather than inefficient code
 - ◆ Disrupts schedules and creates negative user perceptions
 - ◆ Results in poorer overall performance (than building performance into architecture)
 - ◆ May not be possible to achieve requirements with tuning
 - ◆ Increases costs

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Value of Preventing Problems

US Federal Government Software



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Lessons from History



Modernizing Telephone Switch Software

- ◆ Initial implementation of object oriented software resulted in significant performance problems
- ◆ Many OO telephony systems had the same performance problems (Software Performance Antipattern)
- ◆ Preventable with proper tools
- ◆ Risk of new technology and/or inexperienced personnel
- ◆ Problems likely to occur in initial MDE implementation for Embedded Systems

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RTES/Analyzer Performance Modeling

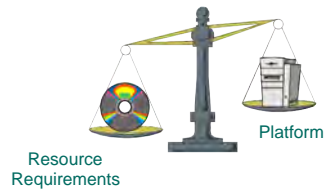


- ❖ Automated assessment of software and systems architecture is essential
 - ◆ We cannot continue to build RTES with yesterday's methods
- ❖ RTES/Analyzer approach
 - ◆ Model interoperability
 - Automated translation of design models to performance models
 - Model solutions translated into meaningful results for developers
 - ◆ Adaptable, extensible evolution of tools

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SPE Balance



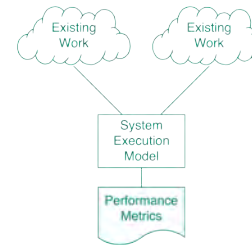
- ❖ Quantitative Assessment
- ❖ Begins early, frequency matches system criticality
- ❖ Often find architecture matches with lower resource requirements
- ❖ Select cost-effective performance solutions early
- ❖ Right-size the platform

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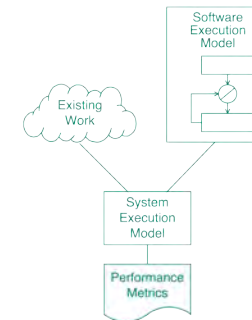
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SPE Models

System Models



Software Prediction Models



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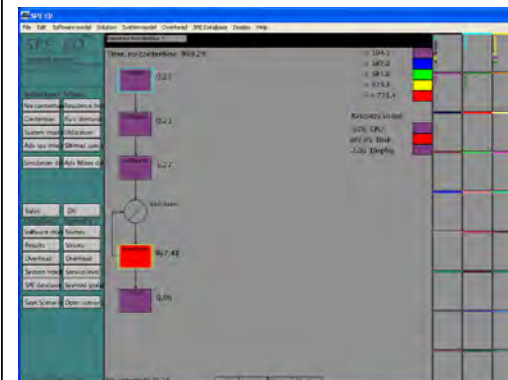
SPE Model Requirements

- ❖ Low overhead
 - ♦ use the simplest possible model that identifies problems
- ❖ Goals:
 - ♦ initially distinguish between "good" and "bad"
 - ♦ later, increase precision of predictions
 - ♦ provide decision support

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11

SPE-ED



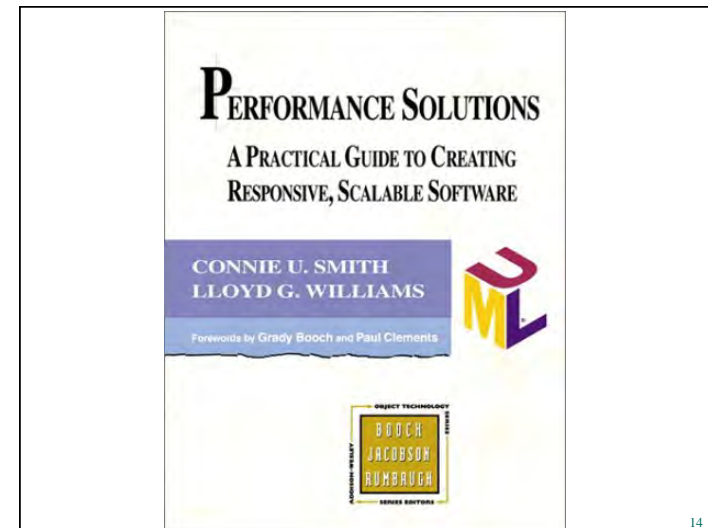
- ❖ Tool for performance engineers
- ❖ Established technology
- ❖ Access to source code for R&D

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Additional SPE Topics

- ❖ Performance Principles
- ❖ Performance Measurement
- ❖ Performance Patterns & Antipatterns
- ❖ Architecture Assessment: PASASM
- ❖ Business Case for SPE
- ❖ SPE Process

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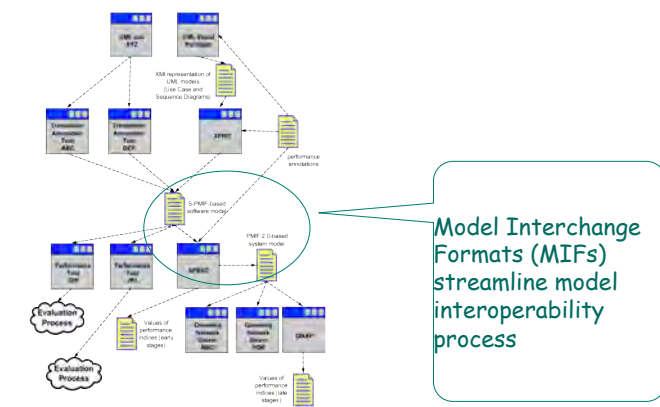
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Part 2: Automating the Model-Driven Analysis



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UML Design Models -> Performance Models



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MIF Approach

- ❖ General approach to be used by a wide variety of tools
 - ♦ EIA EDIF/CDIF paradigm
 - ♦ Meta-model of information requirements
 - ♦ Transfer format based on meta-model
- ❖ XML implementation
 - ♦ Meta-model → schema, transfer format in XML
 - ♦ Relatively easy to create
- ❖ Common interface
 - ♦ No need for n^2 customized interfaces between tools
 - ♦ Import/export can be external to tools with file interfaces

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17

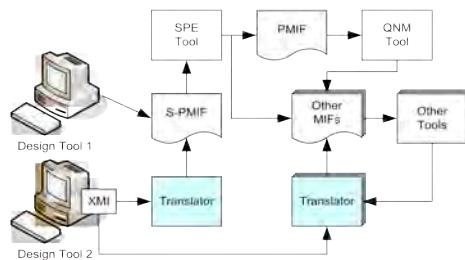
Our Model Interchange Research Results

- ❖ Design tools to software performance models (S-PMIF)
- ❖ System performance models (PMIF)
- ❖ Model solutions
 - ♦ Experiments (Ex-SE)
 - ♦ Output metrics desired from experiments (Output-SE)
 - ♦ Transformation from output to tables and charts (Results-SE)

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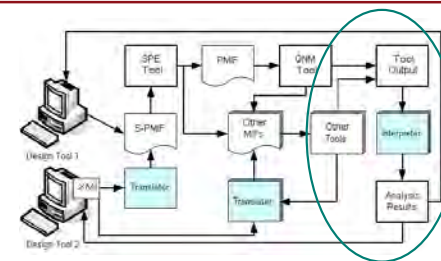
Previous Approach - Several Distinct Steps



- ❖ A proof of concept has been implemented for each step
- ❖ Each step was a separate, independent program
- ❖ Modeling expertise required limits usefulness for developers

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Automated Approach for Developers



- ❖ Want to automate the end-to-end analysis steps:
 - ♦ Transformations, validation, experiment definition, and tool invocation,
 - ♦ Collect and present result data to developers for problem identification and diagnosis

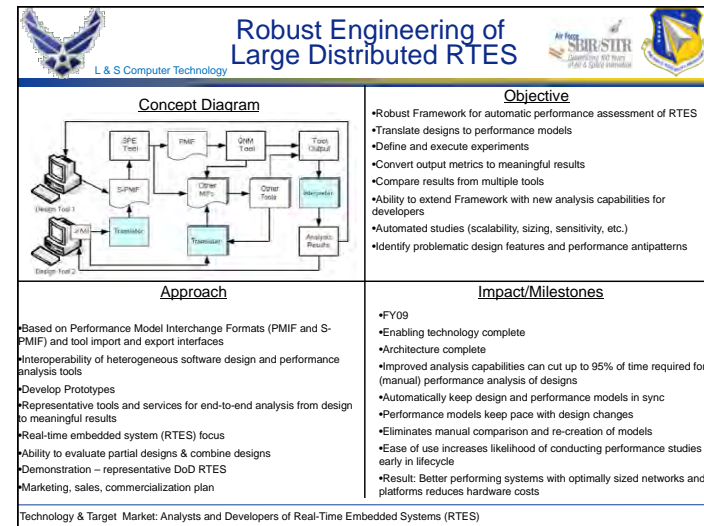
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Vision: Developers Do Robust Engineering

- ❖ Explore options using familiar tools & notations (UML, Eclipse)
- ❖ Select candidate designs for exploration
- ❖ RTES/Analyzer
 - ◆ Select metrics
 - ◆ Specify analysis conditions and select tools
 - ◆ Quantitative predictions from multiple tools
 - ◆ Environment invokes analysis tool(s), collects output, prepares results in user-friendly format
 - ◆ Identify performance antipatterns
- ❖ Bring in performance specialists for serious problems

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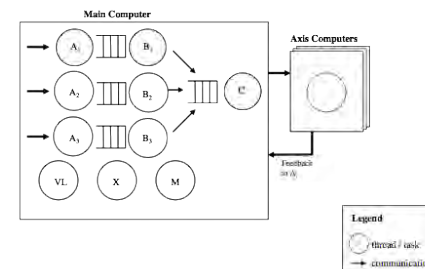


Case Study



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Robot Controller SEI Model Problem

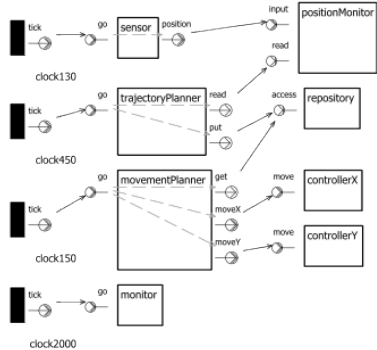


- ❖ Main computer generates work orders
- ❖ Decomposed into subwork orders to axis computer(s)
- ❖ Interpreted by device drivers for movement of robot arms

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Controller Design

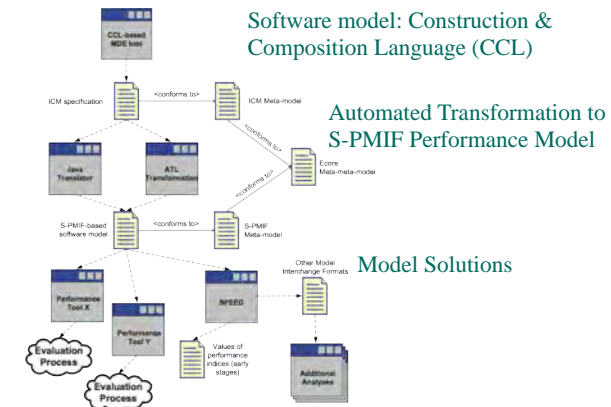


- ❖ Movement planner cannot find repository empty
- ❖ Planners cannot miss deadlines at end of period

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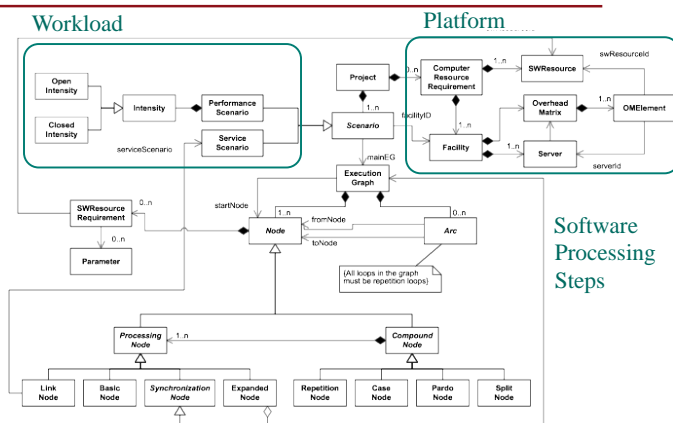
Component Architecture -> Performance Models



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S-PMIF MetaModel



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S-PMIF Excerpt

```

<PerformanceScenario InterarrivalTime="450.0"
MainEG="trajectoryPlanner.go" Priority="4"
ScenarioId="trajectoryPlanner.go"
ScenarioName="trajectoryPlanner.go" SWmodelfilename="icm">

<ExecutionGraph EGId="trajectoryPlanner.go"
EGName="trajectoryPlanner.go"
StartNode="N_trajectoryPlanner.go">

<BasicNode NodeId="N_trajectoryPlanner.go"
NodeName="N_trajectoryPlanner.go">
<SWResourceRequirement SWResourceId="R_CPU"
UnitsOfService="89.665066"/>
</BasicNode>
<SynchronizationNode
NodeId="N_trajectoryPlanner.read_positionMonitor.read"
NodeName="N_trajectoryPlanner.read_positionMonitor.read"
myType="SynchronousCall" partnerId="N_positionMonitor.read"
partnerScenario="positionMonitor.read"/>

```

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Performance Analysis

- ❖ Best and worst case analysis
- ❖ Simple model and advanced model with synchronization
- ❖ Multiple tools
 - ◆ Worst case latency - PSK performance-reasoning framework on linear sequence of actions
 - MAST tool - RMA technique
 - Discrete event simulator
 - ◆ SPE-ED tool

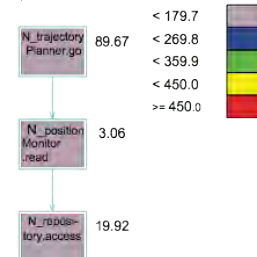
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29

Software Performance Models

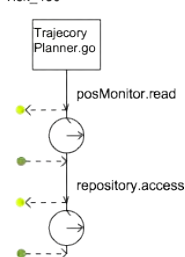
Simple: scenario
per event source (4)

E_trajectoryPlanner.go
Time, no contention: 112.65



Advanced: scenario
per thread with
synchronization (9)

Tick_450



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Model Results

Transaction	Best	Average	Worst
RMA Analytic			
clock130.tick	15.04		98.04
clock450.tick	112.65		262.77
clock150.tick	60.02		79.94
clock2000.tick	0.32		278.14
DE Simulation			
clock130.tick	15.04	33.71	75.08
clock450.tick	247.73	259.49	262.83
clock150.tick	60.02	60.00	60.04
clock2000.tick	0.32	103.08	278.20
SPE-ED Results			
clock130.tick	15.04	33.78	99.07
clock450.tick	112.65	259.67	262.77
clock150.tick	60.02	60.02	60.02
clock2000.tick	0.32	71.61	278.14

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Results

- ❖ Simulation solutions comparable, not exact
 - ◆ DE simulation does not include contention
 - ◆ In best case, response to clock450.tick preempted twice by clock150.tick -> higher response time than no contention best case
- ❖ Simple, best case is optimistic
 - ◆ Identifies problems that must be corrected
 - ◆ Then proceed to more precise evaluations

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Option

- ❖ Replace X and Y controllers with controllers that also provide position feedback to position monitor
 - ♦ Simple model: changes Clock150.tick to make +2 calls
 - ♦ Advanced model: changes ControllerX and ControllerY threads to make asynchronous calls to PositionMonitor.input

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Revised Results

Transaction	Best	Average	Worst
RMA Analytic			
clock130.tick	15.04		124.06
clock450.tick	112.65		496.91
clock150.tick	86.03		109.02
clock2000.tick	0.32		431.24
DE Simulation			
clock130.tick	15.04	52.18	115.99
clock450.tick	314.80	347.63	431.04
clock150.tick	86.03	89.57	105.99
clock2000.tick	16.19	220.18	431.36
SPE-ED Results			
clock130.tick	15.04	46.51	208.16
clock450.tick	112.65	305.60	317.86
clock150.tick	86.03	90.08	192.65
clock2000.tick	0.32	126.68	413.30

Worst-case times differ:

SPE-ED computed average time for all calls to positionMonitor.input
RMA distinguishes between calls from different “clocks” - each has different response time due to pre-emption

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Proof of Concept

- ❖ Demonstrates viability of model interchange approach
- ❖ Builds on work in component-based systems, SPE, and model interchange
- ❖ Helpful to compare solutions from different software performance modeling tools
- ❖ Automation of steps simplifies performance assessment

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Case Study Conclusions

- ❖ S-PMIF transformations can be procedural (custom code) or declarative Model to Model (M2M) transformations
- ❖ Enables performance analysis of CCL specifications with additional analysis tools without special integration efforts
- ❖ Demonstrates viability and ease of using S-PMIF with multiple design notations in addition to UML

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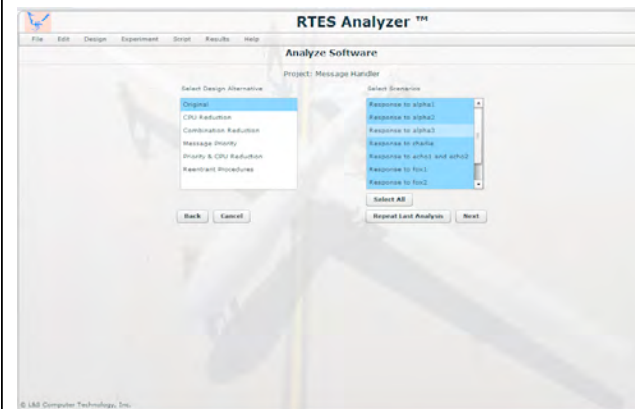
36

RTES/Analyzer: Sample User Interface



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UI Demonstration



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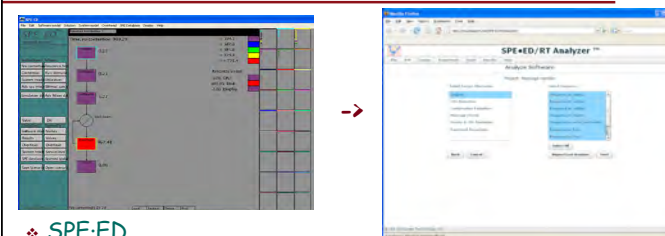
UI Demonstration

- ❖ Demonstrates ease of use for developers
- ❖ Selection of designs and experiments
- ❖ Meaningful results
- ❖ Flashbuilder foundation for Phase 2 implementation

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SPE-ED → RTES/Analyzer



- ❖ SPE-ED
 - ♦ Users are performance experts
 - ♦ Primarily IT systems
- ❖ RTES/Analyzer
 - ♦ Target developers as users
 - ♦ Focus on Real-Time & Embedded System market sector

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RT/Analyzer Addresses Future Needs

- ❖ Cost
 - ◆ Ability to predict performance of designs reduces cost of re-work due to late discovery of problems
 - ◆ Up to 100 times more expensive to fix it later
- ❖ Quality
 - ◆ Systems meet performance requirements
- ❖ Automated Analysis
 - ◆ RT/Analyzer early detection of problems, performance ranking of solutions
 - ◆ Less expertise and shorter time for analysis
- ❖ Productivity
 - ◆ Quicker to build-in performance
 - ◆ Resources can be devoted to development rather than re-work

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Status

- ❖ RTES/Analyzer architecture and enabling technology are positioned for future development
- ❖ SBIR Phase II funding approved
- ❖ Developing prototype RTES/Analyzer to demonstrate the viability of automatic generation and evaluation of performance models, and presentation of quantitative results useful for developers
- ❖ Seeking comprehensive case study data
- ❖ Seeking partners to create commercial products

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Summary



- ❖ Embedded Systems Modeling
- ❖ Software Performance Engineering (SPE) Overview
- ❖ Automating the Model-Driven Analysis
- ❖ Proof of Concept: Component-based RTES

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